



CASToR^[1]: A Generic Data Organization and Processing Code Framework for Multi-Modal and Multi-Dimensional Tomographic Reconstruction

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Motivations for an unified tomographic image reconstruction platform

Natural differences in the dataset acquisition / organization ...

... lead to algorithms optimized for specific applications, with potential drawbacks :

- Restricted use of methodologies however compatible with other sets of conditions
- Difference in duplication of implementations
- Possibly hardly tractable code development

- Modality (PET / SPECT / CT)
- Purpose (tracer dynamics, gated dataset)
- Data format (list-mode/histogram)

Additional drives for an unified platform:

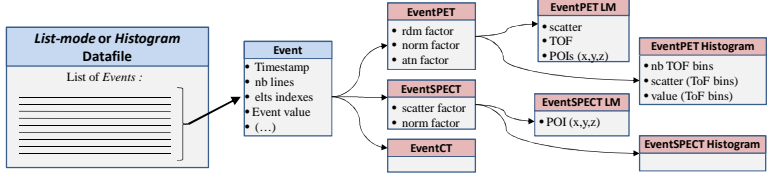
- Analogous components (projector, optimizer, ...) for PET/SPECT/CT tomographic reconstruction
- Re-emergence of iterative reconstruction in CT^[2]

Proposed solution

- Unified and generic data organization and processing code framework for multi-modal and multi-dimensional tomographic reconstruction.
- Analogous data organization for list-mode/histogram
- Compromise between genericity and efficiency
- Focus on the modularity and extensibility of the platform

General data file Description

- Generic *Event* structure for all type of data (modality/data mode)
- Reconstruction framework is *Event*-based
- PET/SPECT *Event* can be of "list-mode" type (i.e. single detected event) or histogram type (i.e. content of a histogram bin).
- *Events* must contain mandatory fields: *timestamp*, *event value*, *geo localizer indices* and optionally : *TOF*, *scatter/random rate*, *norm factors*, etc... (optional fields)



Implementation

- C++ open-source platform (CASToR^[1])
- 3 levels of temporal dimension :

- Dynamic frames
- Respiratory gating
- Cardiac gating

- Events loop step equal to the number of subsets (Fig. 1)
- Subsets balance respected for both list-mode / histogrammed data.

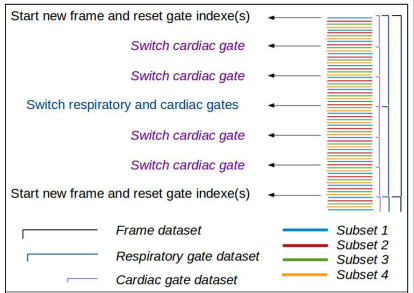
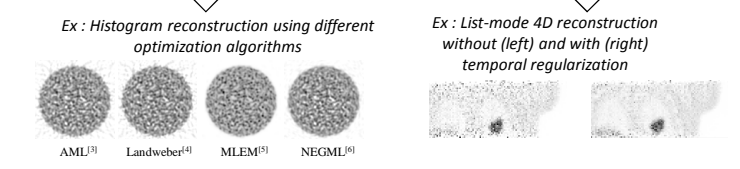
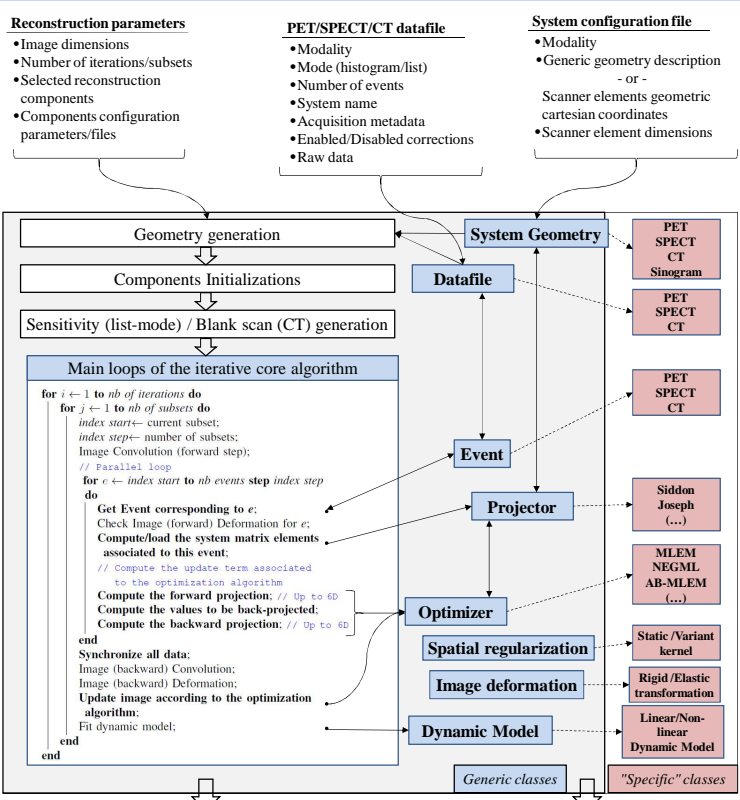


Fig.1 : Organization and processing of a 6D dataset in an OSEM framework

CASToR^[1] Iterative framework



- Separation of Generic and Specific classes favors limited duplication of implementations
- Generic implementation of each reconstruction component allows easy integration of new methodologies

Results

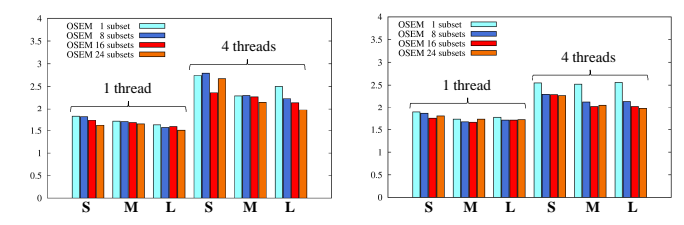
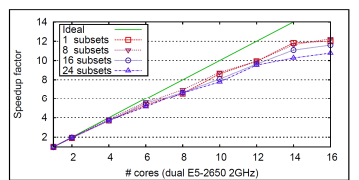


Fig.2 : Speed-up ratio of CASToR OSEM reconstructions compared to standard "2-calls to projector" implementation:
 - List-mode (10M prompts) : 88x88x63 (S), 175x175x125 (M), 350x350x250 (L) 4,2,1mm³ voxels
 - Histogram (45M events) : 128x128x50 (S), 256x256x100 (M), 512x512x200 (L) 4,2,1mm³ voxels

- Improved computational efficiency (ratios from 1.5 to 2.75) due to the separation of the computation of the system matrix elements from the actual projections

Fig.3 : Speed-up factor with respect to the number of threads for a 3D reconstruction



- Computing efficiency presented limited dependence on the number of subsets

Conclusions & Perspectives

- Proposed architecture handles histogram/list-mode multi-modal and multi-dimensional iterative reconstruction
- Simplified integration of new reconstruction features / methodologies, with limited duplication of implementations
- Good computing performances in its parallel execution (Unique call to the projector by event allowed a 1.5 to 2.75 increase speedup ratios on the test platform, as well as moderate cost of genericity)
- Proposed implementation will be soon available through an open-source software^[1]

References

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